




**IMU/VRU/AHRS**

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# U300-A INDUSTRIAL GRADE

MEMS IMR/VRU/AHRS



## GYROSCOPES

Maximum dynamic range .....	±100 °/sec
Bias in-run stability (Alan) .....	5 °/hr
Bias in-run repeatability (Alan) .....	5 °/hr
Noise (Random walk) .....	0.12 °/√h
Scale factor error .....	0.08 %FS

Size .....59.6 x 59 x 23.5 mm

Weight .....120 g

## ACCELEROMETERS

.....±10 /±20 /±40 g
.....0.05 mg
.....0.12 mg
.....0.03 m/sec/√h
.....0.1 %FS



# U300-B INDUSTRIAL GRADE

MEMS IMU



## GYROSCOPES

## ACCELEROMETERS

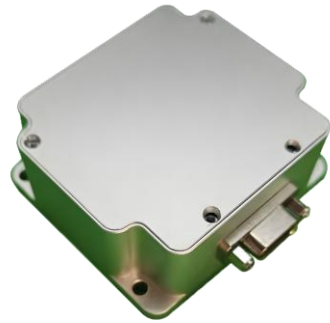
Maximum dynamic range .....	...±125/250/500/1000 °/sec	.....±3 /6 /12/24 g
Bias in-run stability (Alan) .....	.....7 °/hr	.....0.08 mg
Bias in-run repeatability (Alan) .....	.....7 °/hr	.....0.18 mg
Noise (Random walk) .....	.....0.12 °/√h	.....0.09 m/sec/ √ h
Scale factor error .....	.....0.1 %FS	.....0.1 %FS

Size .....22 x22 x 7.4 mm

Weight .....7 g

# U3000 INDUSTRIAL GRADE

MEMS IMU/VRU/AHRS



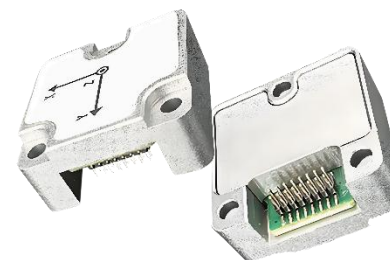
	GYROSCOPES	ACCELEROMETERS
Maximum dynamic range .....	±100 °/sec	±10/20/40 g
Bias in-run stability (Alan) .....	3 °/hr	0.05 mg
Bias in-run repeatability (Alan) .....	3 °/hr	0.12 mg
Noise (Random walk) .....	0.09 °/√h	0.03 m/sec/ √ h
Scale factor error .....	0.08 %FS	0.1 %FS
Size .....	59.6 x53.4 x 24 mm	
Weight .....	120 g	





# U3500-A/B/C/D INDUSTRIAL GRADE

MEMS IMU/VRU/AHRS



	<b>GYROSCOPES</b>	<b>ACCELEROMETERS</b>
Maximum dynamic range .....	.....±2000 (adjustable) °/sec	.....±12(adjustable) g
Bias in-run instability (Alan) .....	.....3~2 °/hr	.....0.03~0.018 mg
Pitch/Roll (Static/Dynamic).....	0.15~0.2 °/hr	
Heading angle drift (Static).....	0.15~0.2 °/hr	
Heading angle drift (Dynamic).....	9~5 °/hr	
Magnetometer range.....	±20Gauss	
Barometer range.....	300-1200hPa	
Size .....	22 x22 x 10 mm	
Weight .....	8 g	
Connector model .....	Molex/Board to board	
Interface .....	UART(TTL)/CAN/IO	

# U3600-A/B/C INDUSTRIAL GRADE

MEMS IMU/VRU/AHRS



## GYROSCOPES

Maximum dynamic range .....  $\pm 2000$  (adjustable)  $^{\circ}/\text{sec}$   
 Bias in-run instability (Alan) .....  $3 \sim 1.6$   $^{\circ}/\text{hr}$

## ACCELEROMETERS

.....  $\pm 12$  (adjustable) g  
 .....  $0.03 \sim 0.018$  mg

Pitch/Roll (Static/Dynamic).....  $0.15 \sim 0.2$   $^{\circ}/\text{hr}$   
 Heading angle drift (Static).....  $0.15 \sim 0.2$   $^{\circ}/\text{hr}$   
 Heading angle drift (Dynamic).....  $9 \sim 5$   $^{\circ}/\text{hr}$   
 Magnetometer range.....  $\pm 20$  Gauss  
 Barometer range..... 300-1200hPa  
 Size ..... 25.7 x 24 x 12 mm  
 Weight ..... 11 g  
 Connector model ..... USB  
 Interface ..... USB





# U3700-A/B/C/D INDUSTRIAL GRADE

MEMS IMU/VRU/AHRS

	<b>GYROSCOPES</b>	<b>ACCELEROMETERS</b>
Maximum dynamic range .....	..... $\pm 2000$ (adjustable) °/sec	..... $\pm 12$ (adjustable) g
Bias in-run instability (Alan) .....	.....3~1.2 °/hr	.....0.03~0.018 mg
Pitch/Roll (Static/Dynamic).....	.....0.15~0.2 °/hr	
Heading angle drift (Static).....	.....0.15~0.2 °/hr	
Heading angle drift (Dynamic).....	.....9~5 °/hr	
Magnetometer range.....	..... $\pm 8$ Gauss	
Size .....	.....58.5 x40 x 20 mm	
Weight .....	.....75 g	
Connector model .....	.....USB	
Interface .....	.....UART(RS-232/TTL)/RS485/CAN/USB	

# U5000 TACTICAL GRADE

MEMS IMU



## GYROSCOPES

Maximum dynamic range .....	±400 °/sec
Bias in-run stability (10s, 1σ) .....	3°/hr
Bias in-run repeatability (10s, 1σ).....	3°/hr
Noise (Random walk).....	0.15 °/√h
Scale factor nonlinearity.....	100ppm

Size .....	44.8 x38.6 x 21.5 mm
Weight .....	60 g
Interface .....	RS232/RS422

## ACCELEROMETERS

.....	±30 g
.....	0.1 mg
.....	0.1 mg
.....	0.17 m/sec/ √ h
.....	1000ppm



# U6300 TACTICAL GRADE

MEMS IMU/VRU/ARHS



	GYROSCOPES	ACCELEROMETERS
Maximum dynamic range .....	$\pm 450$ °/sec	$\pm 20$ g
Bias in-run stability (10s, $1\sigma$ ) .....	1°/hr	0.1 mg
Full temp bias in-run stability.....	5°/hr	0.15 mg
Noise (Random walk).....	0.03 °/ $\sqrt{h}$	0.02 m/sec/ $\sqrt{h}$
Scale factor nonlinearity.....	100ppm	100ppm
Size .....	44.8 x38.6 x 10 mm	
Weight .....	60 g	
Interface .....	RS422	

# U7000-A/B TACTICAL GRADE

MEMS IMU/VRU/AHRS



## GYROSCOPES

Maximum dynamic range .....	±400 °/sec
Bias in-run stability (10s, 1σ) .....	0.3~1°/hr
Full temp bias in-run stability .....	2~10°/hr
Noise (Random walk) .....	0.02~0.05 °/√h
Scale factor nonlinearity .....	100ppm

Size .....	44.8 x38.6 x 21.5 mm
Weight .....	55 g
Interface .....	RS232/RS422

## ACCELEROMETERS

.....	±30 g
.....	0.1 mg
.....	1 mg
.....	0.01 m/sec/√h
.....	500ppm



# U6488-A/B/C/D TACTICAL GRADE

MEMS IMU/VRU/AHRS



	<b>GYROSCOPES</b>	<b>ACCELEROMETERS</b>
Maximum dynamic range .....	±450 °/sec	±20 g
Bias in-run stability (10s, 1σ) .....	1~4°/hr	0.1 ~0.5mg
Full temp bias in-run stability.....	5~8°/hr	0.15~1 mg
Noise (Random walk).....	0.03~0.08 °/√h	0.02~0.05 m/sec/ √ h
Scale factor nonlinearity.....	100ppm	100~200ppm
Size .....	47 x44 x 14 mm	
Weight .....	40 g	
Interface .....	SPI	

# U16488-A/B/C TACTICAL GRADE

MEMS IMU/VRU/AHRS



## GYROSCOPES

Maximum dynamic range .....	±500 °/sec
Zero bias instability (Allan curve) .....	0.3~1°/hr
Full temp bias in-run stability.....	8°/hr
Noise (Random walk).....	0.1~0.03 °/√h
Scale factor nonlinearity.....	200ppm

Size .....	47 x44 x 14 mm
Weight .....	40 g
Interface .....	SPI

## ACCELEROMETERS

.....	±20 g
.....	0.02 ~0.04mg
.....	0.3~1 mg
.....	0.02~0.03 m/sec/√h
.....	200ppm



# UF100A TACTICAL GRADE

FOG Based IMU



	<b>GYROSCOPES</b>	<b>ACCELEROMETERS</b>
Maximum dynamic range .....	±300 °/sec	±10 g
Bias in run stability (10s.1σ) .....	0.2°/hr	0.5mg
Bias in run repeatability (10s.1σ) .....	0.2°/hr	0.5mg
Noise (Random walk).....	0.04 °/√h	0.01 m/sec/ √ h
Scale factor nonlinearity.....	100ppm	300ppm
Size .....	φ84.6 x 77.2 mm	
Weight .....	820 g	
Interface .....	RS422	

# UF300-A/B/C NAVIGATION GRADE

FOG Based IMU



Maximum dynamic range .....	±300/1000 °/sec
Bias in run stability (10s.1σ) .....	0.05~0.1°/hr
Bias in run repeatability (10s.1σ) .....	0.05~0.1°/hr
Noise (Random walk).....	0.005~0.01 °/√h
Scale factor nonlinearity.....	50~60ppm

Size .....	145x 125x 122 mm
Weight .....	1800 g
Interface .....	RS422

## GYROSCOPES

## ACCELEROMETERS

.....	±10 g
.....	0.05~0.07mg
.....	0.05~0.07mg
.....	0.007m/sec/ √ h
.....	100~300ppm



# UF3X80-A/UF3X80-B TACTICAL GRADE

FOG Based IMU



Maximum dynamic range .....	±500 °/sec
Bias in-run stability (1σ, 10s) .....	0.3/0.5 °/hr
Bias repeatability (1σ) .....	0.3/0.5 °/hr
Noise (Random walk) .....	0.03/0.02 °/√h
Scale factor error .....	30/50 ppm
Size .....	φ80 × 70 mm
Weight .....	680 ±50 g

## GYROSCOPES

## ACCELEROMETERS

..... Can be customized according to customer's requirement either made by MEMS Accelerometers or by Quartz Accelerometers

# UF3X90-A/UF3X90-B TACTICAL GRADE

FOG Based IMU



	<b>GYROSCOPES</b>
Maximum dynamic range .....	±500 °/sec
Bias in-run stability (1σ, 10s) .....	0.1/0.2 °/hr
Bias repeatability (1σ) .....	0.1/0.2 °/hr
Noise (Random walk) .....	0.01/0.02 °/√h
Scale factor error .....	30/50 ppm
Size .....	φ90 × 78 mm
Weight .....	780 ±50 g

**ACCELEROMETERS**  
..... Can be customized according to customer's requirement either made by MEMS Accelerometers or by Quartz Accelerometers



# UF3X100-A/UF3X100-B NAVAIGATION GRADE

FOG Based IMU



Maximum dynamic range .....	±500 °/sec
Bias in-run stability (1 $\sigma$ , 10s) .....	0.05/0.1 °/hr
Bias repeatability (1 $\sigma$ ) .....	0.05/0.1 °/hr
Noise (Random walk) .....	0.005/0.003 °/ $\sqrt{h}$
Scale factor error .....	30/30 ppm
Size .....	100 x 100 x 95 mm
Weight .....	950 $\pm$ 50 g

## GYROSCOPES

## ACCELEROMETERS

..... Can be customized according to customer's requirement either made by MEMS Accelerometers or by Quartz Accelerometers

# UF700 TACTICAL GRADE

FOG and MEMS Accl Combined IMU

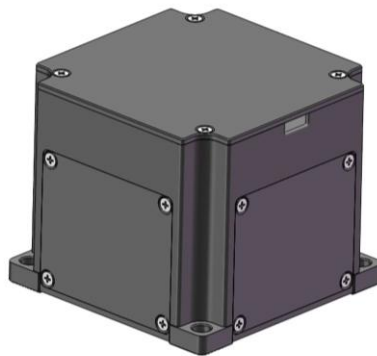


	GYROSCOPES	ACCELEROMETERS
Maximum dynamic range .....	±800 °/sec	±30 g
Bias in-run stability (Allan) .....	0.5 °/hr	0.06 mg
Bias repeatability (1σ) .....	0.5 °/hr	0.06 mg
Noise (Random walk) .....	0.05 °/√h	0.01 m/sec/√h
Scale factor error .....	100 ppm	100 ppm
Size .....	80 x 80 × 60 mm	
Weight .....	1000 g	



# UF600 TACTICAL GRADE

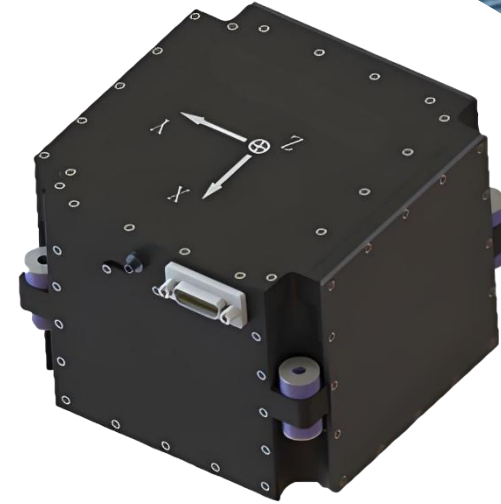
FOG and MEMS Accl Combined IMU



	GYROSCOPES	ACCELEROMETERS
Maximum dynamic range .....	±900 °/sec .....	±50 g .....
Bias in-run stability (Allan) .....	0.2 °/hr .....	0.2 mg .....
Bias repeatability (1σ) .....	0.2 °/hr .....	0.2 mg .....
Noise (Random walk) .....	0.05 °/√h .....	0.01 m/sec/√h .....
Scale factor error .....	100 ppm .....	100 ppm .....
Size .....	63 x 63 x 53mm	
Weight .....	350 g	

# RU1000 TACTICAL GRADE

RLG Based IMU



	<b>GYROSCOPES</b>	<b>ACCELEROMETERS</b>
Maximum dynamic range .....	1000 °/sec	±30 g
Bias in run stability (10s.1σ) .....	0.1°/hr	0.05mg
Bias in run repeatability (10s.1σ) .....	0.1°/hr	0.05mg
Noise (Random walk).....	0.02°/√h	0.009m/sec/ √ h
Scale factor nonlinearity.....	20ppm	50ppm
Size .....	105x 105x 80 mm	
Weight .....	1400±200g	
Interface .....	RS422	





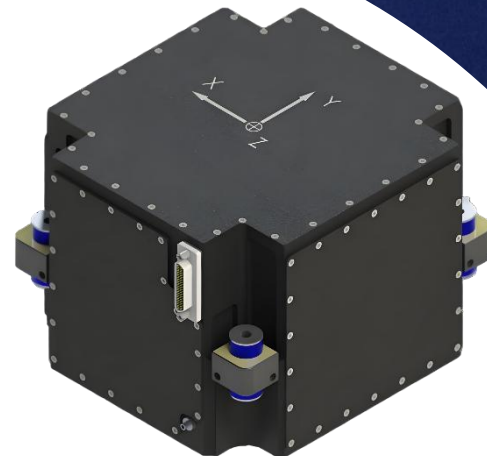
# RU2000 NAVIGATIONAL GRADE

RLG Based IMU

	<b>GYROSCOPES</b>	<b>ACCELEROMETERS</b>
Maximum dynamic range .....	500 °/sec	±30 g
Bias in run stability (10s.1σ) .....	0.01°/hr	0.03mg
Bias in run repeatability (10s.1σ) .....	0.008°/hr	0.03mg
Noise (Random walk).....	0.002°/√h	0.008m/sec/√h
Scale factor nonlinearity.....	10ppm	30ppm
Size .....	150x 140x 115 mm	
Weight .....	3300±200g	
Interface .....	RS422	

# RU3000 NAVIGATIONAL GRADE

RLG Based IMU

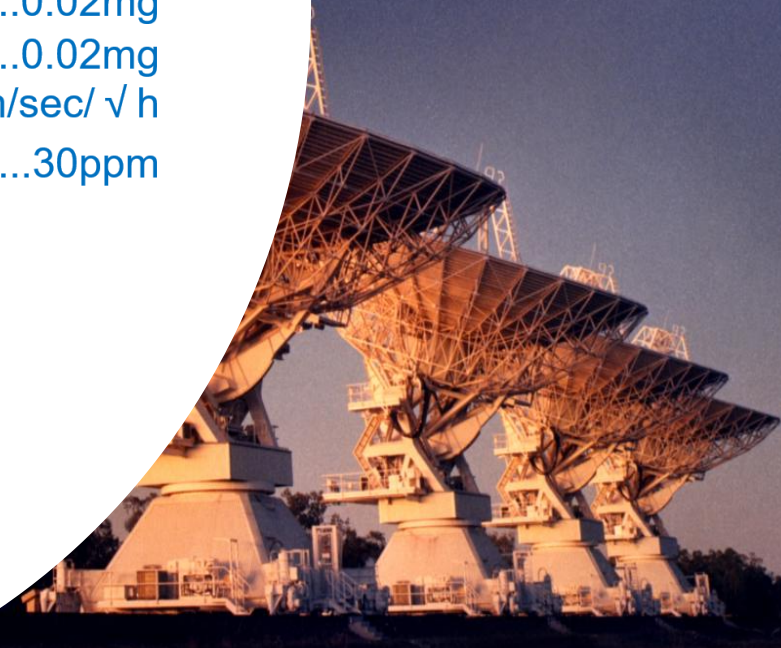


## GYROSCOPES

## ACCELEROMETERS

Maximum dynamic range .....	500 °/sec	±30 g
Bias in run stability (10s.1σ) .....	0.005°/hr	0.02mg
Bias in run repeatability (10s.1σ) .....	0.0025°/hr	0.02mg
Noise (Random walk).....	0.001°/√h	0.006m/sec/ √ h
Scale factor nonlinearity.....	10ppm	30ppm

Size .....	160x 150x 115 mm
Weight .....	3300±200g
Interface .....	RS422





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Unmanned Aerial Vehicles



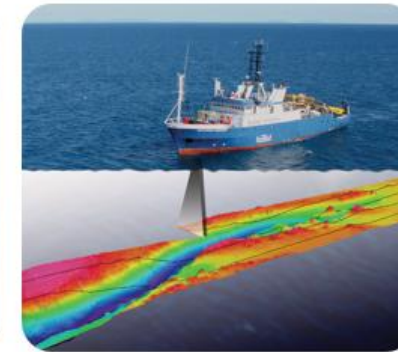
Satellites



Autonomous Vehicles



Remotely Operated Underwater Vehicles



Maritime Echosounder Application



Petroleum Extraction and Exploration